

20070510

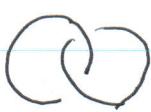
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### Lecture 1

Goal: Introduce the link invariant known as the Jones polynomial and explain its extension to tangles



knot

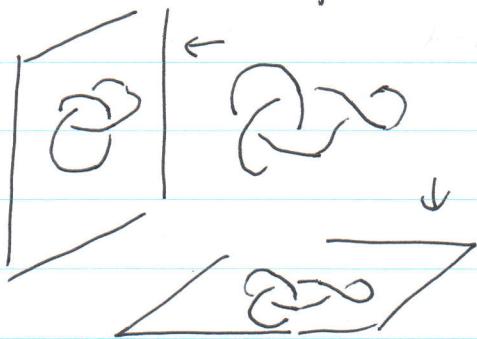


link



tangle

Assign data to planar projection such that it does not depend on the projection chosen



### Th (Reidemeister)

Two link diagrams represent isotopic links iff one can be obtained from the other by a finite sequence of moves

(R1)

$$\text{Diagram 1} \leftrightarrow \text{Diagram 2} \leftrightarrow \text{Diagram 3}$$

(R2)

$$\text{Diagram 1} \leftrightarrow \text{Diagram 2}$$

(R3)

$$\text{Diagram 1} \leftrightarrow \text{Diagram 2}$$

Kauffman bracket:

If  $L$  is a link diagram, let

$[L] \in \mathbb{Z}[a, a^{-1}]$  be defined by

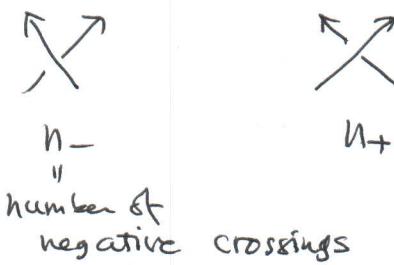
(i)  $[\textcircled{0}] = 1$

(ii)  $[\textcircled{0} \sqcup L] = (-a^2 - a^{-2})[L]$  where  $L \neq \emptyset$

(iii)  $[\textcircled{X}] = a[\textcircled{\cup}] + a^{-1}[\textcircled{\cap}]$

This is almost a link invariant. It is invariant under R2 and R3, but not R1

If we demand that  $L$  is oriented



Then for a link diagram  $L$  the polynomial

$$f[L] = \underbrace{(-a)^{-3(n_+ - n_-)}}_{\text{scaling}} [L]$$

Jones used

$$J(L) = f[L] \Big|_{a=t^{-1/4}}$$

$$(R1) [\text{R}] = a[\text{R}] + a^{-1}[\text{R}] \quad \text{by (iii)}$$

$$= a(-a^2 - a^{-2})[\text{R}] + a^{-1}[\text{R}] = -a^3[\text{R}]$$

orient



$$n_+ = 1, n_- = 0$$

$$f[\text{R}] = -a^{-3}(-a^3)f[\text{R}] = f[\text{R}]$$

$$[\text{R}] = a[\text{R}] + a^{-1}[\text{R}]$$

$$= a[\text{R}] + a^{-1}(-a^2 - a^{-2})[\text{R}] = -a^{-3}[\text{R}]$$

$n_+$

$$f[\text{R}] = (-a^3)(-a^{-3})f[\text{R}]$$

$$(R2) [\text{X}] = a[\text{X}] + a^{-1}[\text{X}]$$

$$\begin{aligned} n_+ &= 1 \\ n_- &= 1 \end{aligned} \quad = a(-a^{-3})[\text{X}] + a^{-1}(a[\text{X}] + a^{-1}[\text{X}])$$

$$= [ ) ( ]$$

Exercise Prove (R3)

Hint Use R2

Warning : Khovanov uses the "scaled" Kauffman bracket  $\langle L \rangle$

$$(i) \langle \phi \rangle = 1$$

$$(ii) \langle O \sqcup L \rangle = (g + g^{-1}) \langle L \rangle$$

$$(iii) \langle X \rangle = \langle \text{X} \rangle - g \langle ) ( \rangle$$

The two are related by  $g \rightarrow -a^2$

The Jones poly. in Khovanov's normalization

$$\hat{J}(L) = (-1)^{n_-} g^{n_+ - 2n_-} \langle L \rangle$$

$$\widehat{J}(L)_{(f=-a^2)} = f(L)(-a^2 - a^{-2})$$

Cor. A knot  $K$  whose Jones polynomial is not symmetric under  $a \rightarrow a^{-1}$  is distinct from its mirror (chiral)

mirror of  $L$        $X \leftrightarrow X$

### Example

$$1) [\text{O} \text{O}] = a [\text{B}] + a^{-1} [\text{B}]$$

$$= -a^4 - a^{-4}$$

from our (R1) calculation

$$2) [\text{O} \text{O}] = a [\text{B}] + a^{-1} [\text{B}]$$

$$= a(-a^4 - a^{-4}) + a^{-1}(a^{-3})^2$$

(Ex 1) from Q calc.

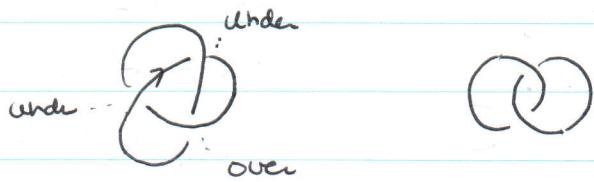
$$= -a^5 - a^{-3} + a^{-7}$$

Not symmetric under  $a \rightarrow a^{-1}$

$\Rightarrow$  trefoil is chiral.

Application : Tait conjecture

A link diagram is alternating if the crossing change  
over under as you go around the link



Tait conj.

A reduced (not of the form  
alternating link



diagram is minimal (i.e. least number  
of crossings)

Note: there may be many diagrams with the same number  
of crossings

Proof

• width of the Jones polynomial

:  $\leq 4$  times the number of crossings

difference of

the highest and

lowest power of  $a$

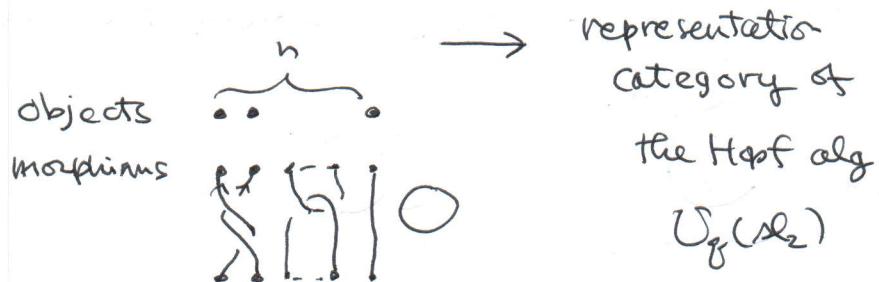
• width of the Jones polynomial for a reduced  
alternating diagram = 4 times //

Different proof using  
Khovanov hom.

## Relationship to $U_q(\mathfrak{sl}_2)$

We can extend the Jones polynomial to a functor

Tang:



$$\begin{array}{ccc} \text{objects} & \xrightarrow{J} & U^{\otimes n} \\ \text{morphisms} & \xrightarrow{J} & U^{\otimes 2} \\ \text{---} & \uparrow \leftarrow \text{intertwines} & \uparrow \xrightarrow{J} \\ \text{---} & \text{the } U_q(\mathfrak{sl}_2) & \text{---} \\ \text{---} & \vdots \text{actions} & \text{---} \\ \text{ground} & & \text{---} \\ \text{ring} & & \text{---} \end{array}$$

$\text{---}$ : 2-dim. irrep.  
of  $U_q(\mathfrak{sl}_2)$

$$X \xrightarrow{J} J(U) - g^{-1} J()()$$

$$T \xrightarrow{J} U^{\otimes m} \quad \xrightarrow{J(T)} \quad \begin{matrix} U^{\otimes m} \\ \uparrow \\ U^{\otimes n} \end{matrix}$$

operator  
which  
intertwines  
the action

$$L = \bigcirc \quad \xrightarrow{J(L)} \quad \begin{matrix} f_k \\ \uparrow \\ f_k \end{matrix}$$

$f_k = \mathbb{Z}[g, g^{-1}]$